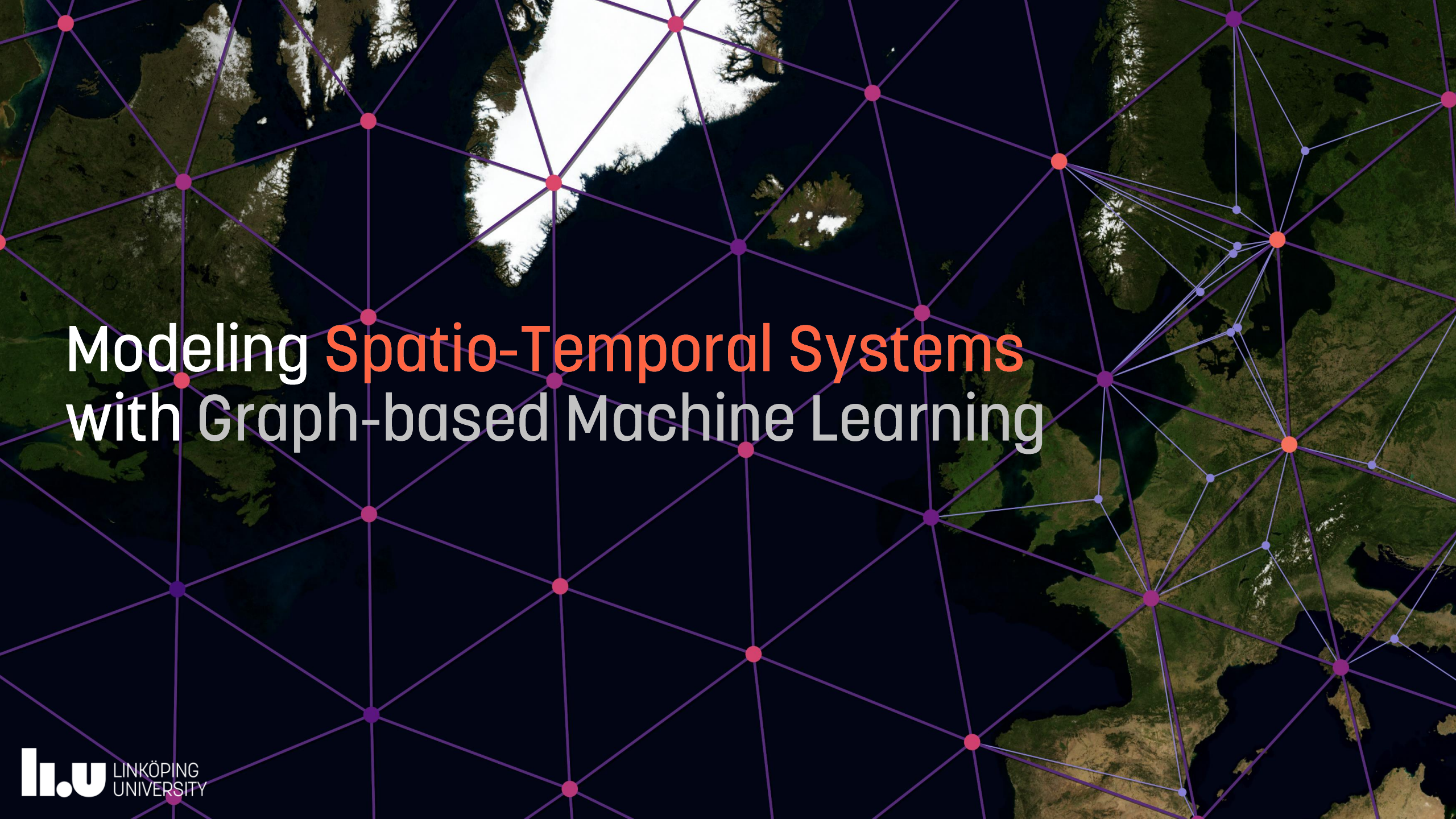


# Modeling Spatio-Temporal Systems with Graph-based Machine Learning

Joel Oskarsson

Division of Statistics and Machine Learning  
Department of Computer and Information Science

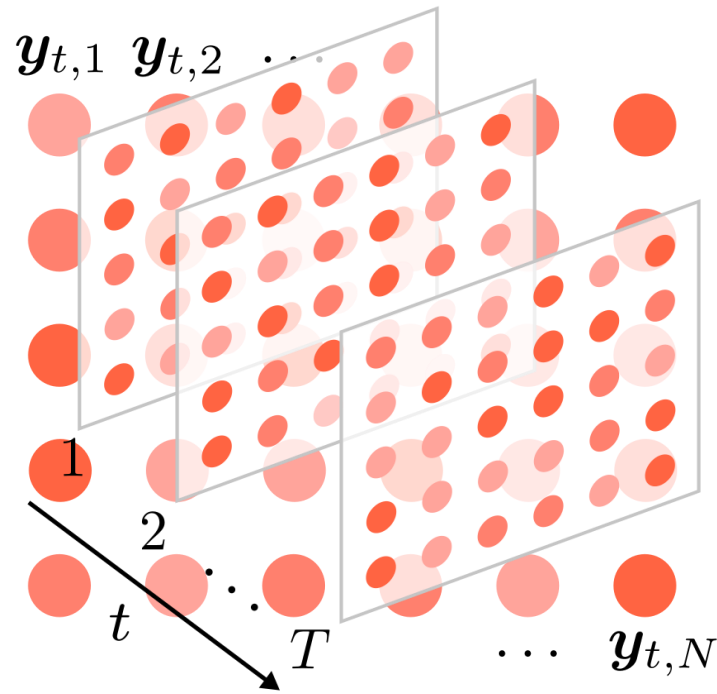


# Modeling **Spatio-Temporal Systems** with Graph-based Machine Learning

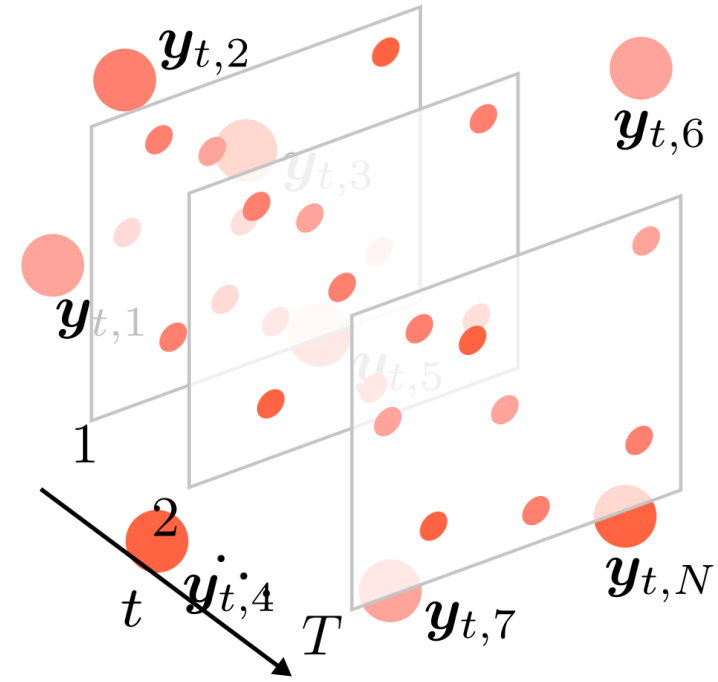
# Spatio-temporal systems



# Spatio-temporal data

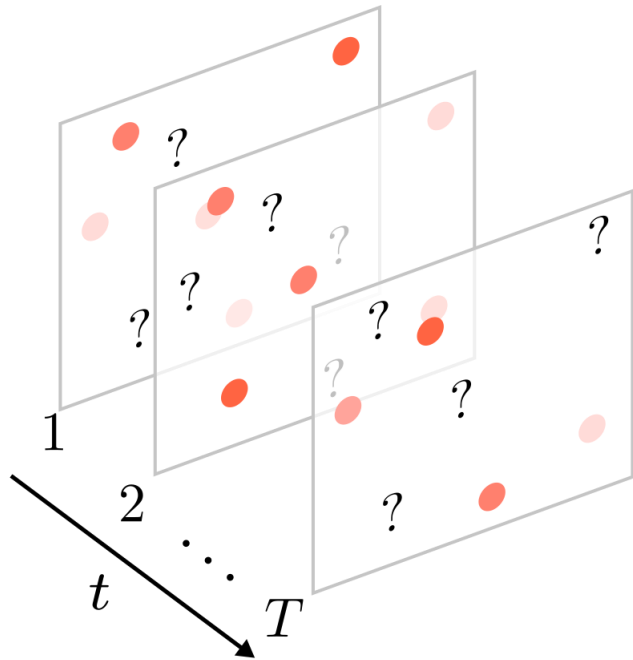


Regular grid

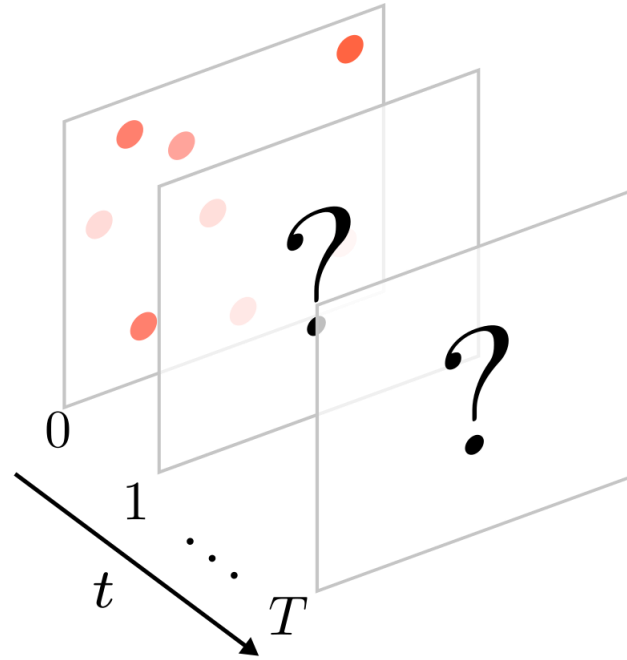


Irregular grid

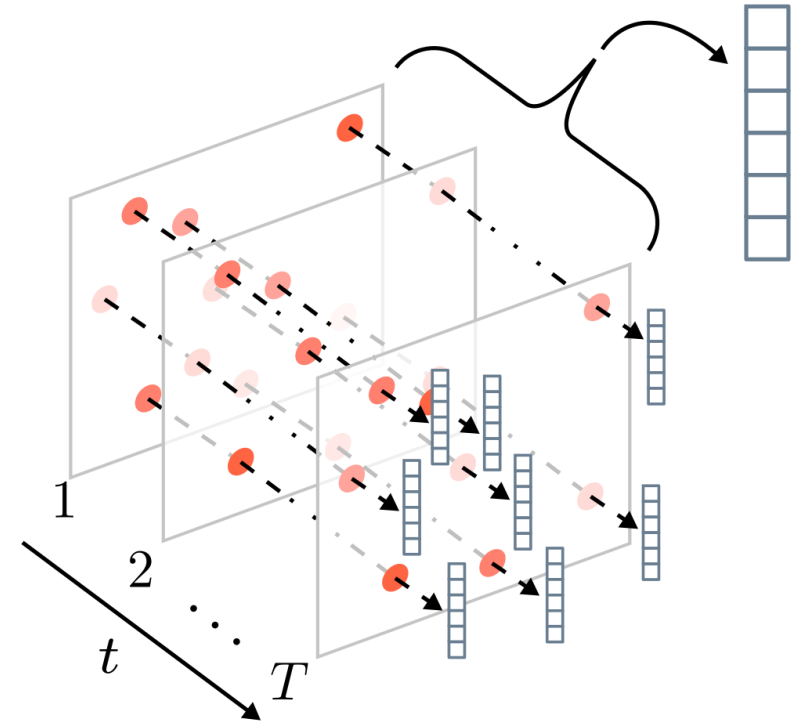
# Machine learning problems



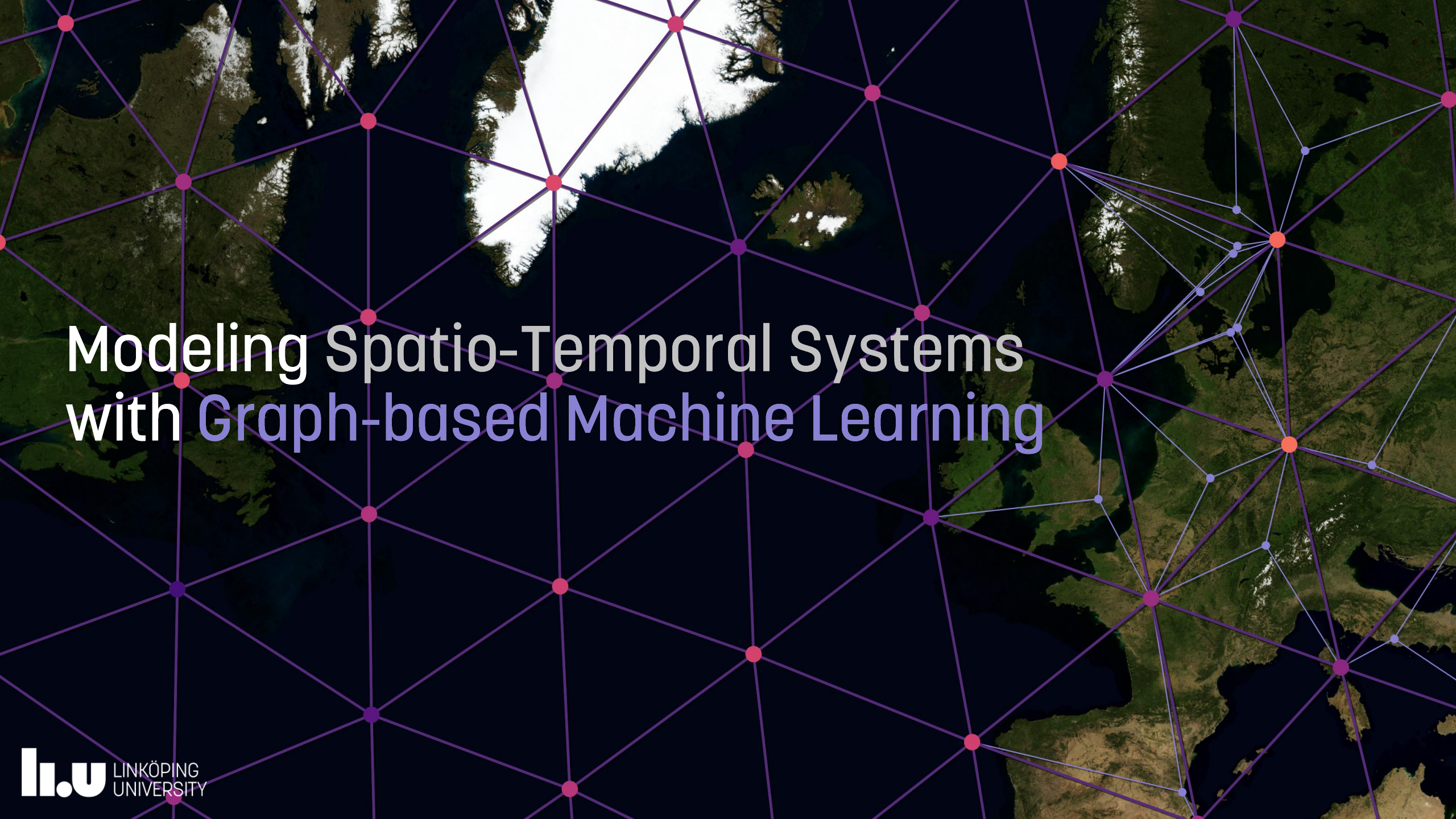
Prediction at new  
times and locations



Forecasting



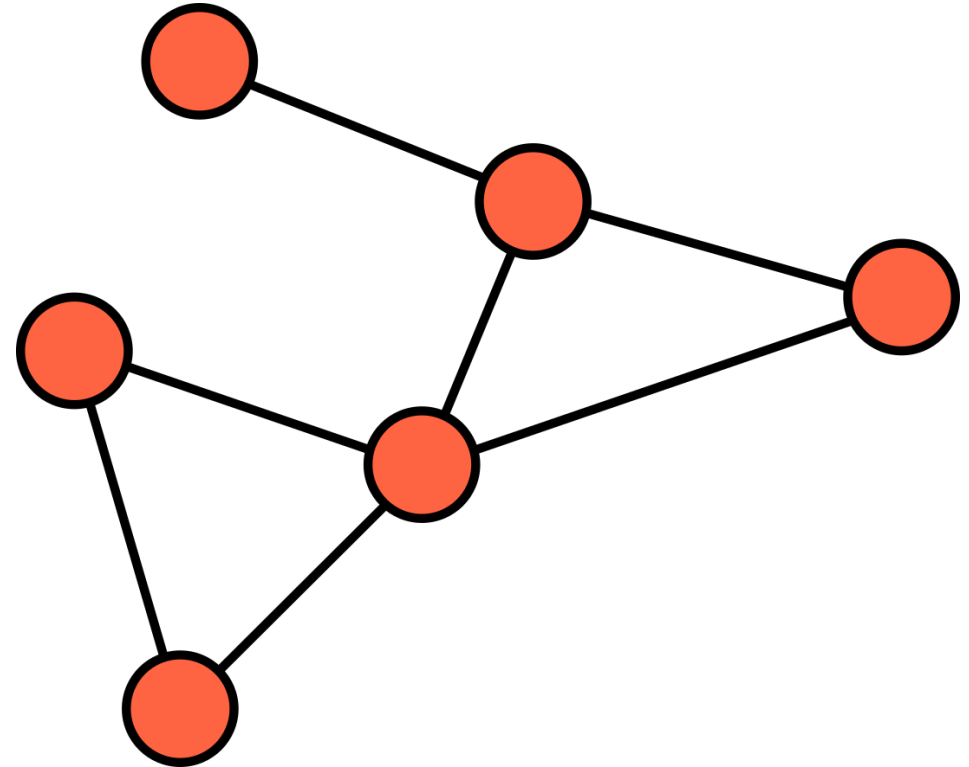
Representation learning



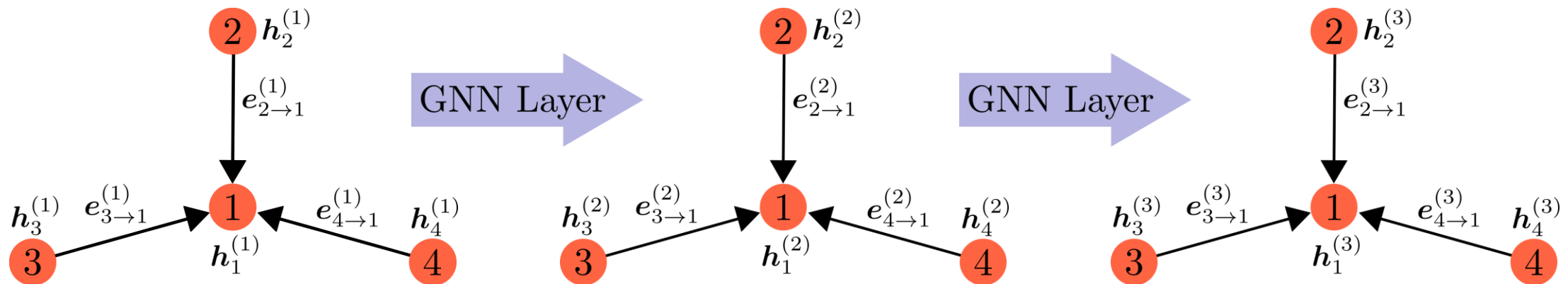
# Modeling Spatio-Temporal Systems with Graph-based Machine Learning

# Graph-based machine learning

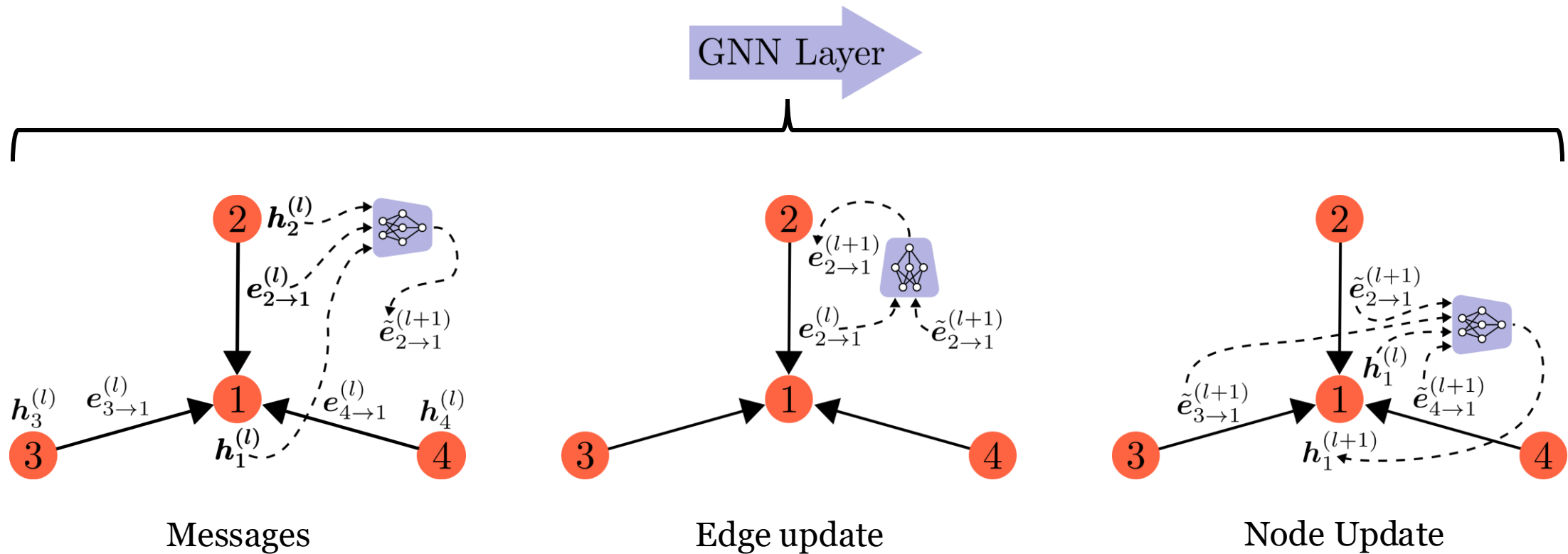
- Graph  $\mathcal{G} = (V, E)$ 
  - Nodes  $V$
  - Edges  $E$
  - Encoding spatial relationships
- Probabilistic graphical models
- Graph Neural Networks (GNNs)



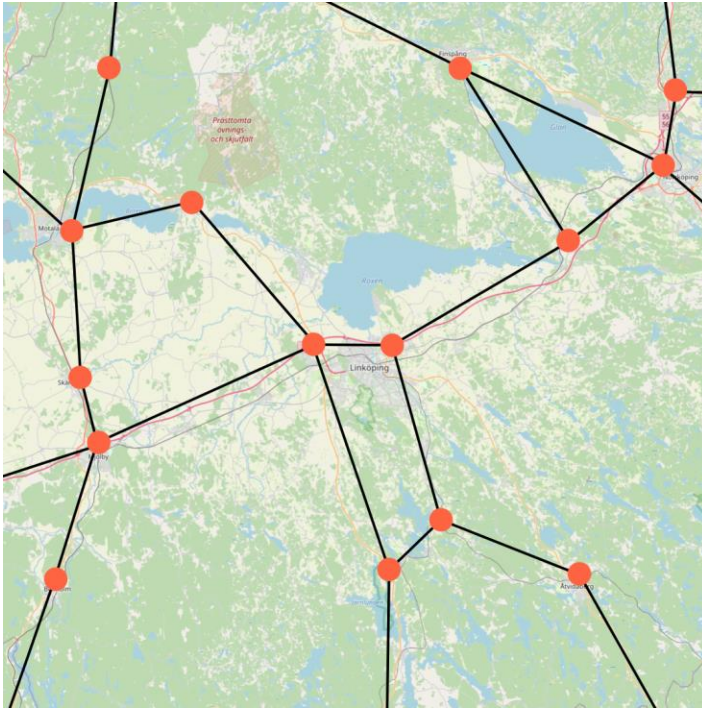
# Graph Neural Networks (GNNs)



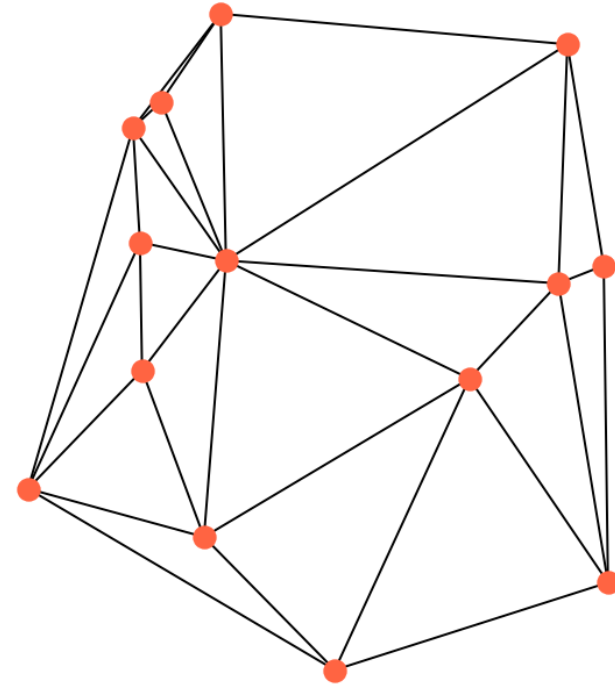
# GNN Layer<sup>1</sup>



# Spatial graphs

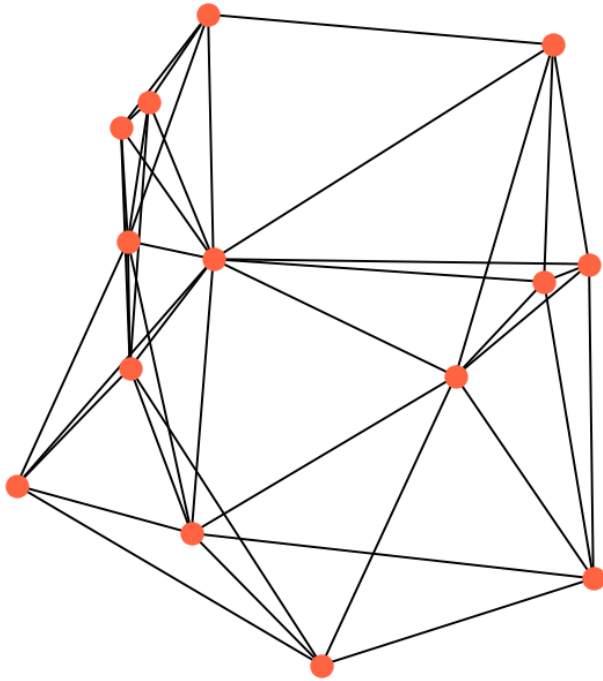


Existing spatial networks<sup>1</sup>

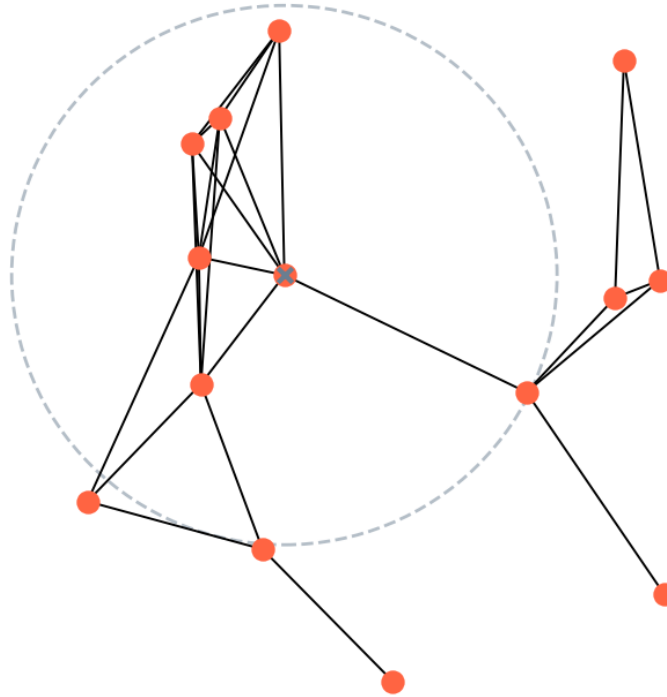


Sets of spatial points

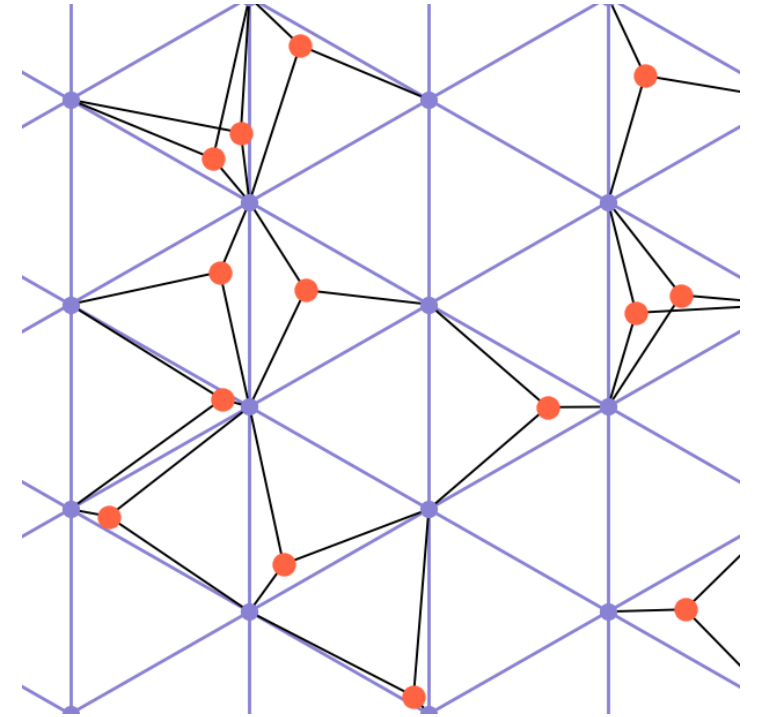
# Spatial graph connectivity



k-nearest neighbors graph

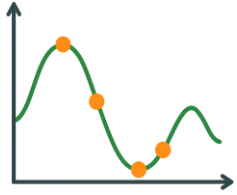


Radius graph



Connect to mesh graph

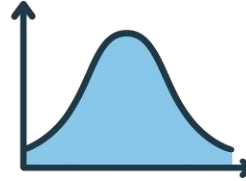
# Papers



Paper 1  
AISTATS 2023



Paper 2  
IEEE IV 2023



Paper 3  
ICML 2022



Paper 4  
NeurIPS 2024



Paper 5  
Preprint, under review

---

## Temporal Graph Neural Networks for Irregular Data

---

**Joel Oskarsson**  
Linköping University

**Per Sidén**  
Linköping University  
Arriver Software AB

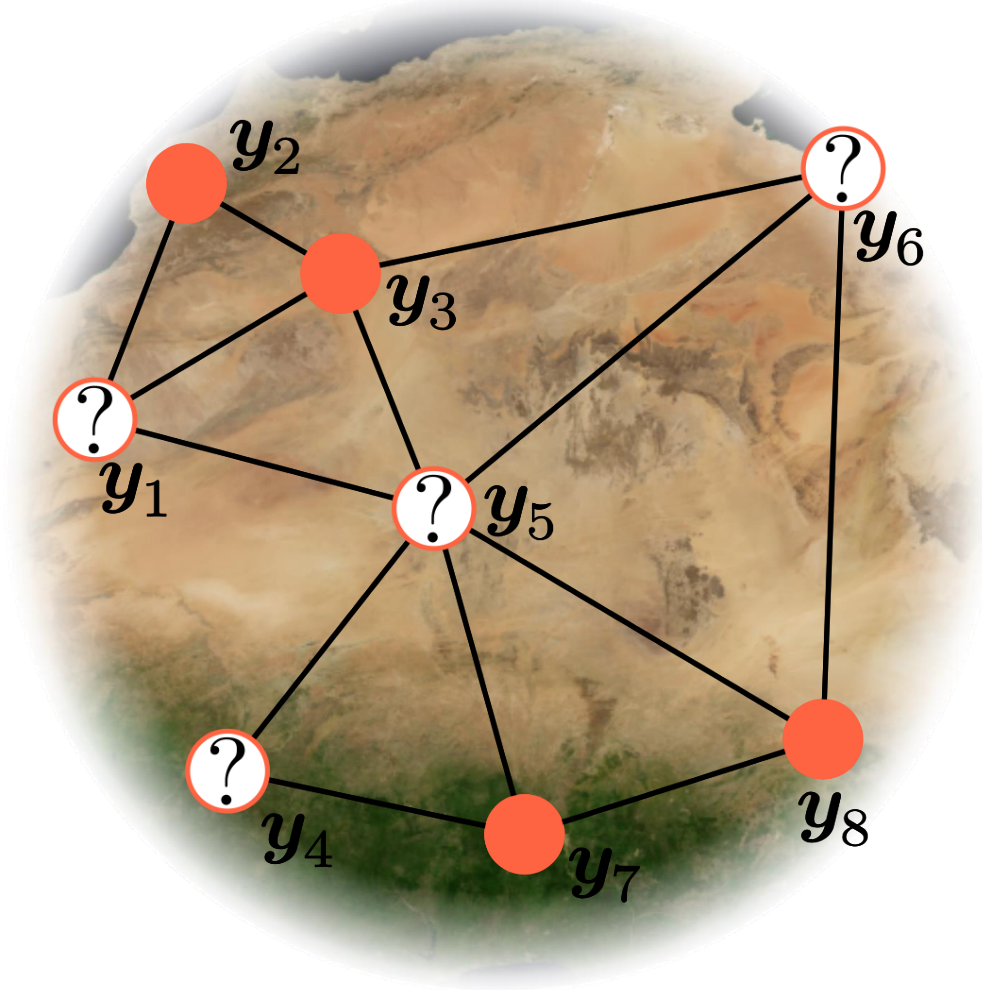
**Fredrik Lindsten**  
Linköping University

### Abstract

This paper proposes a temporal graph neural network model for forecasting of graph-structured irregularly observed time series. Our TGNN4I model is designed to handle both irregular time series and missing observations. Contact: [m.deisenroth@ucl.ac.uk](mailto:m.deisenroth@ucl.ac.uk)

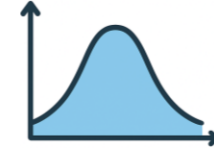
While many works have studied the problem of modeling temporal graph data (Wu et al., 2020a), these approaches generally assume a constant sampling rate and no missing observations. In real data it is not uncommon to have irregular or missing observations due to non-synchronous measurements or errors in the data collection process. Deal with this by using a model that can handle irregular data. Contact: [fredrik.lindsten@liu.se](mailto:fredrik.lindsten@liu.se)

# Prediction at unobserved locations



- Example applications:
  - Climate monitoring
  - Social networks

- Gaussian models



$$\begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{bmatrix} = (z + \epsilon) \sim \mathcal{N}(\mu, Q^{-1} + \sigma^2 I)$$

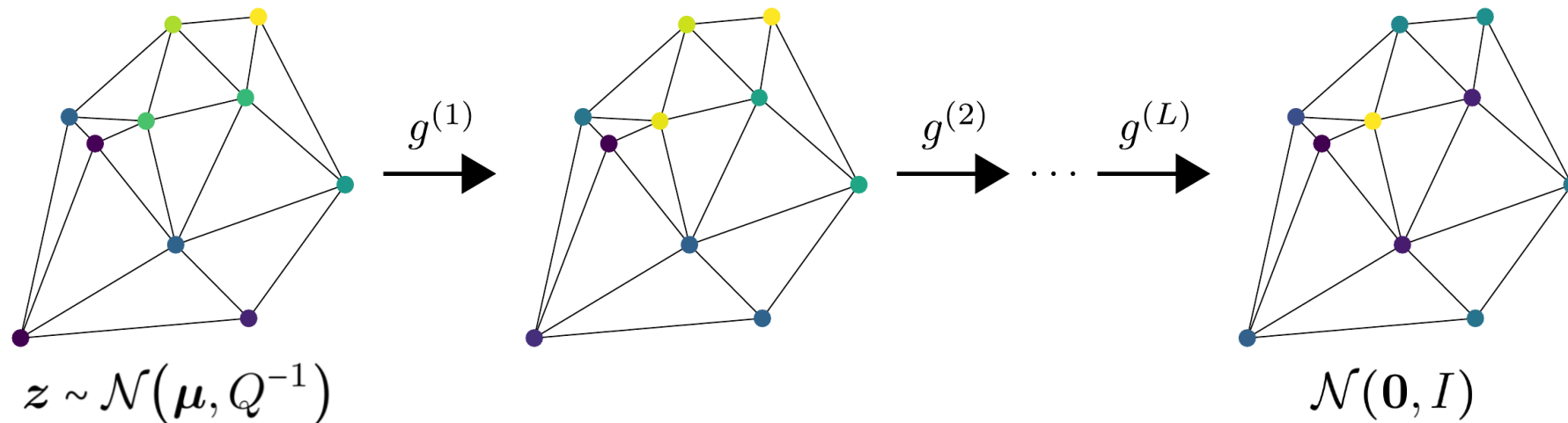
$$\epsilon \sim \mathcal{N}(\mathbf{0}, \sigma^2 I)$$

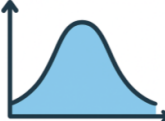
# Deep Gaussian Markov random fields

$$z \sim \mathcal{N}(\mu, Q^{-1})$$

$$g(z) \sim \mathcal{N}(0, I)$$

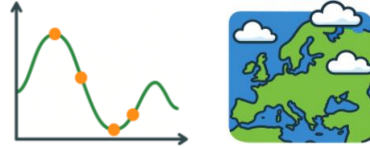
$$g = g^{(L)} \circ g^{(L-1)} \circ \dots \circ g^{(1)}$$



- Previous work<sup>1</sup>: Regular grids  $\Rightarrow$   Paper 3: General graphs

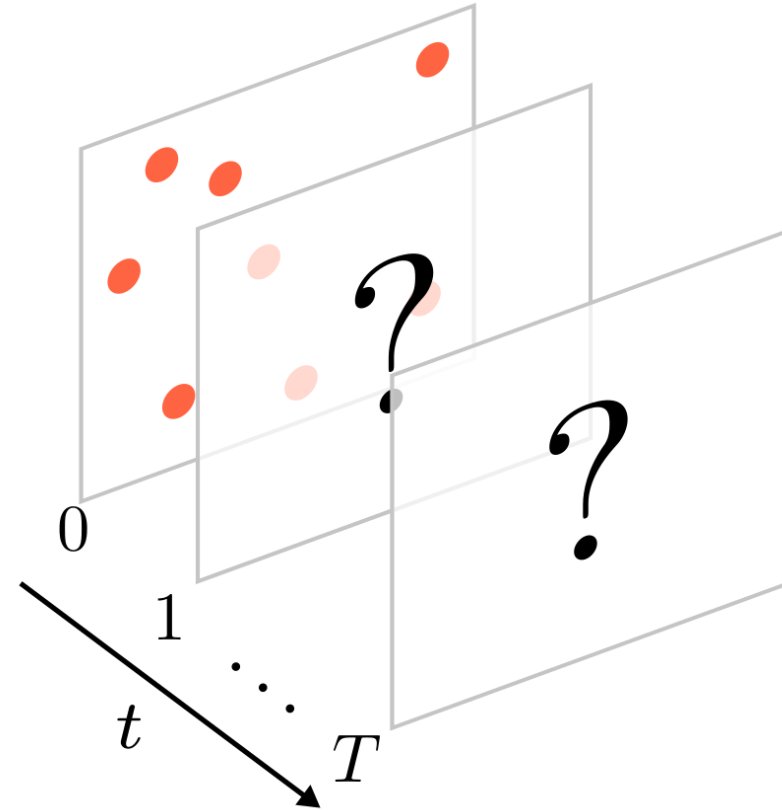
# Spatio-temporal forecasting

- Deterministic forecasting



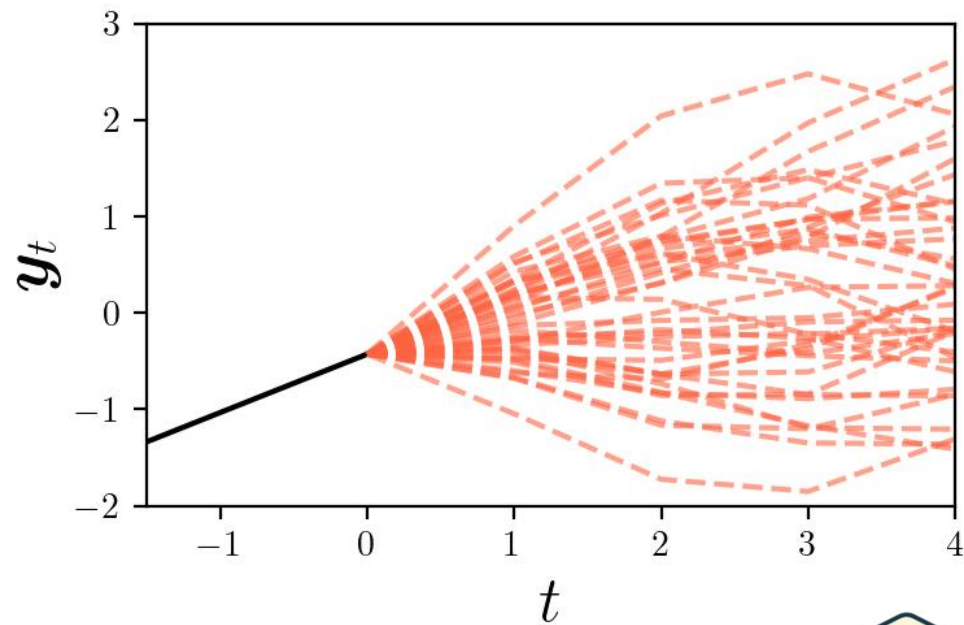
$$(\hat{Y}_t)_{t=1}^T = f(Y_0)$$

$$Y_t = \begin{bmatrix} \text{---} & \mathbf{y}_{t,1}^\top & \text{---} \\ \text{---} & \mathbf{y}_{t,2}^\top & \text{---} \\ & \vdots & \\ \text{---} & \mathbf{y}_{t,N}^\top & \text{---} \end{bmatrix}$$

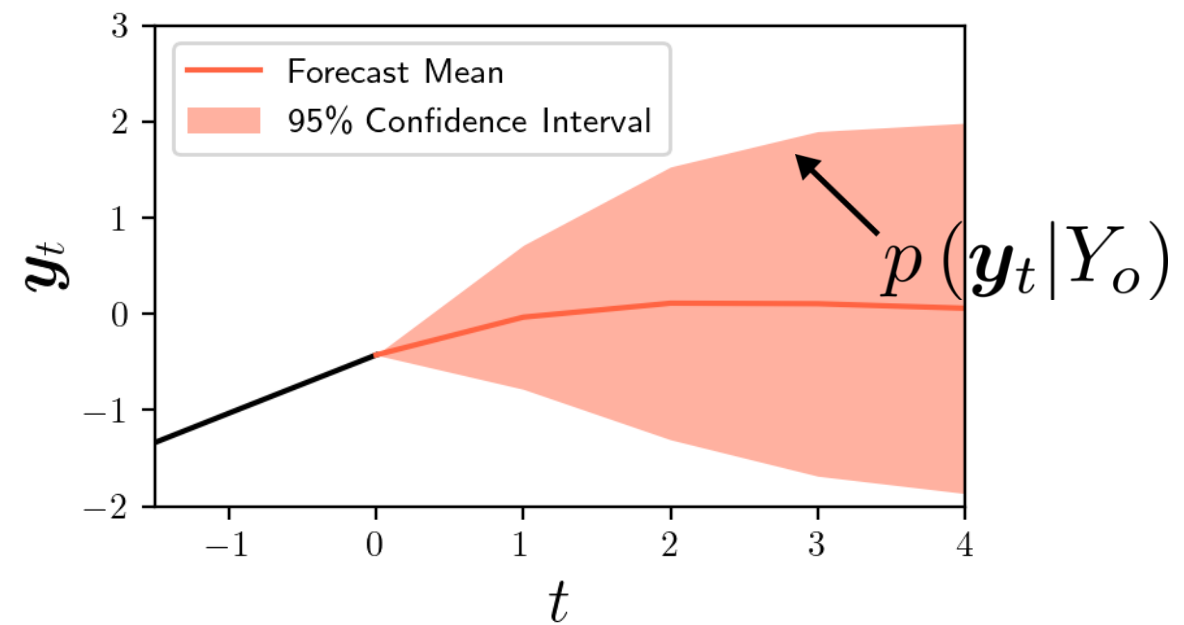


# Probabilistic forecasting

$$p\left((Y_t)_{t=1}^T \middle| Y_0\right)$$



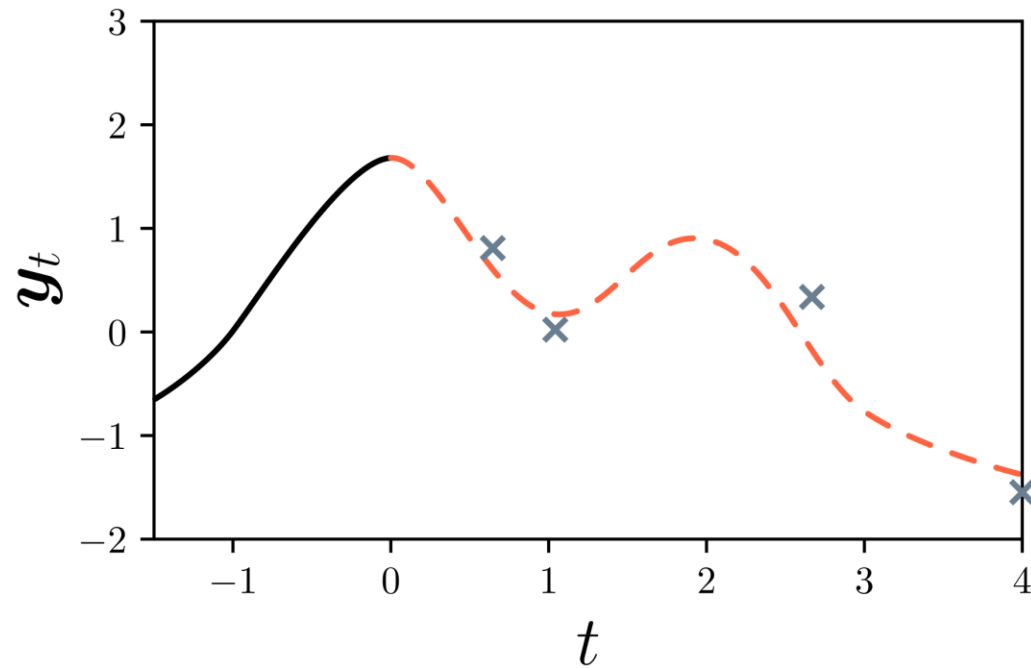
Sample-based  
(Ensemble forecasting)

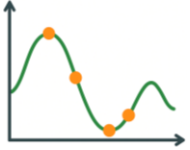



Explicit distribution



# Continuous time



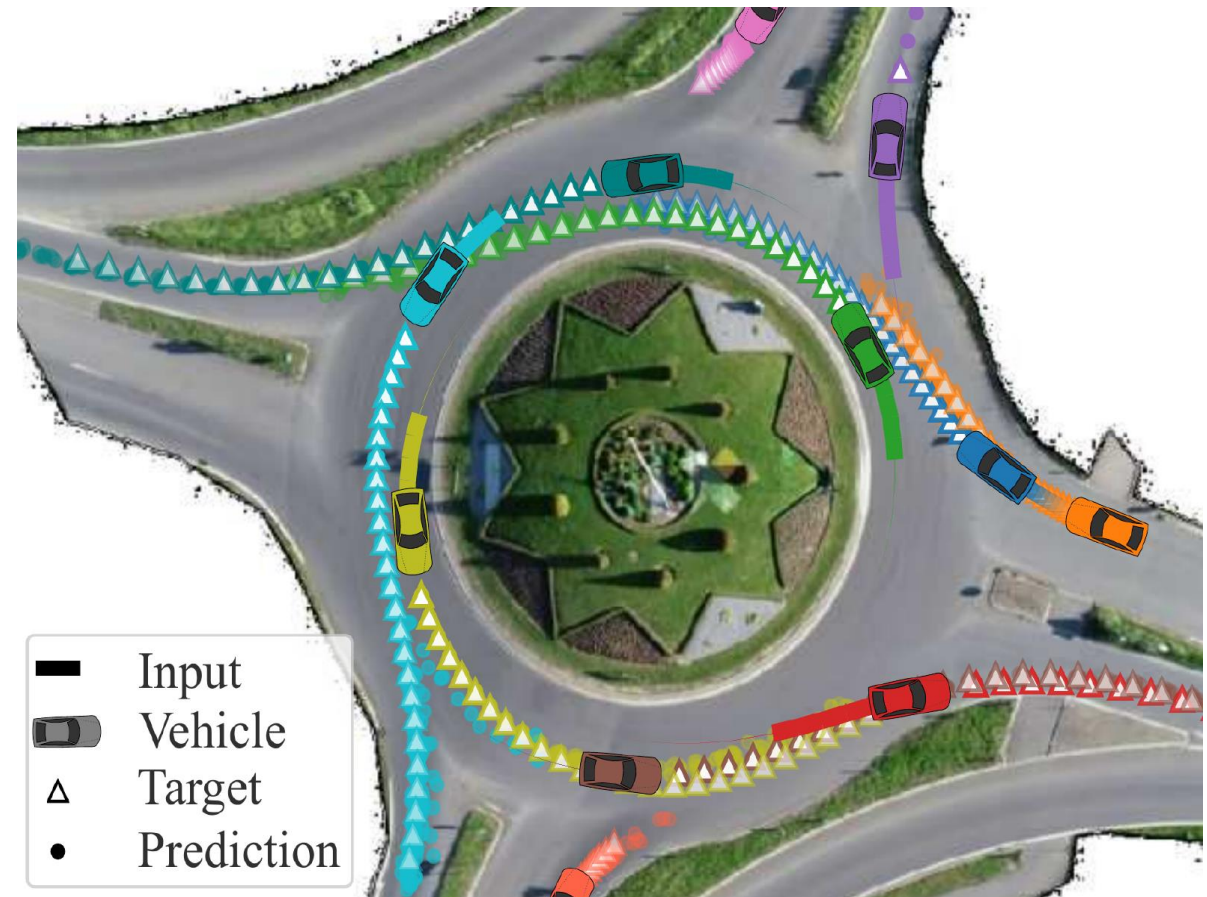
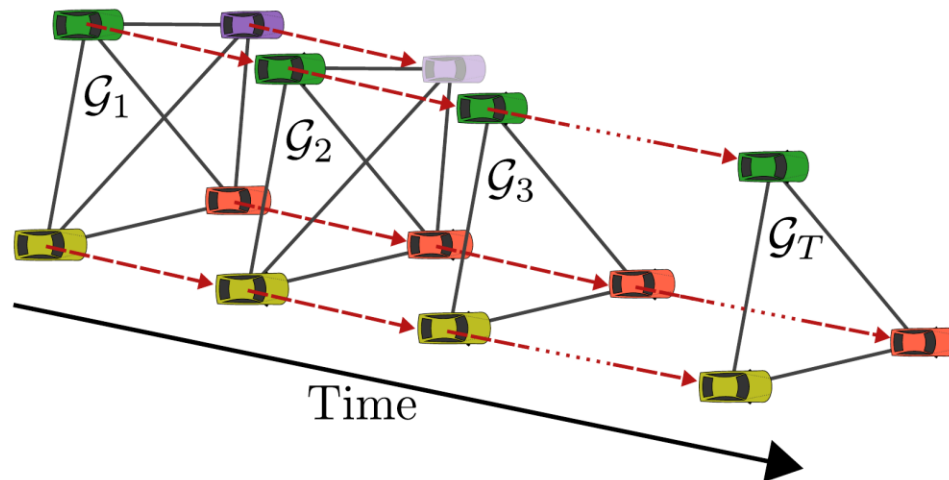
- Irregular observations 
  - Paper 1: In spatio-temporal forecasting with GNNs

- Constraining dynamics 
  - Neural Ordinary Differential Equations<sup>1</sup>

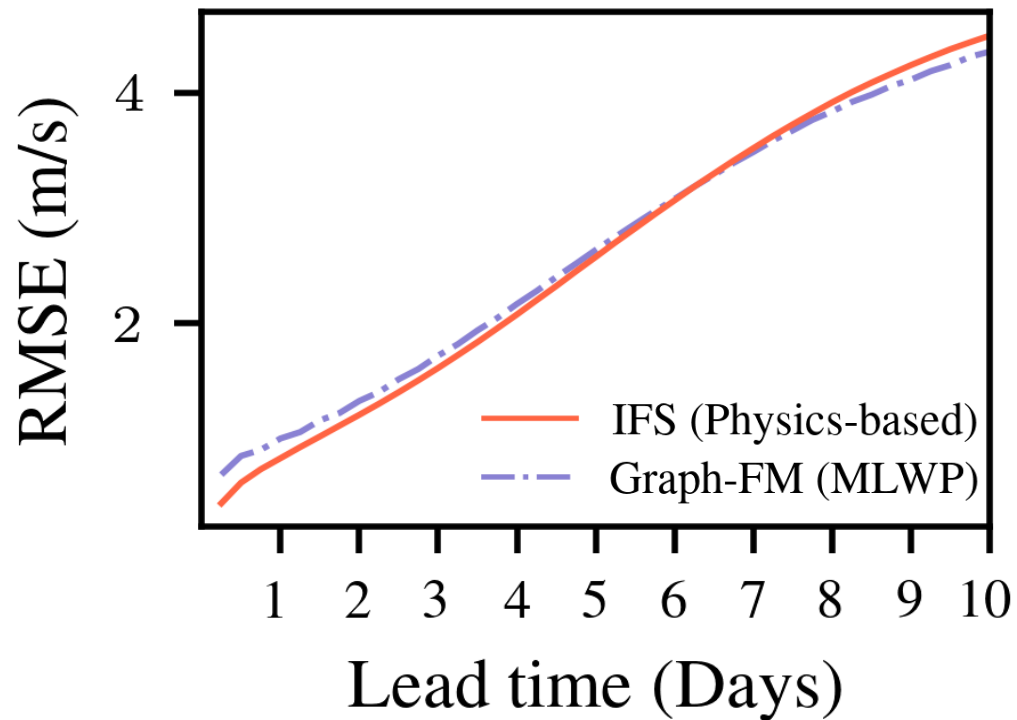
$$\frac{d}{d\tau} \mathbf{y}(\tau) = f_{\theta}(\mathbf{y}(\tau), \dots)$$

# Trajectory forecasting

- Forecasted values are locations
- Multi-agent



# Machine Learning Weather Prediction (MLWP)



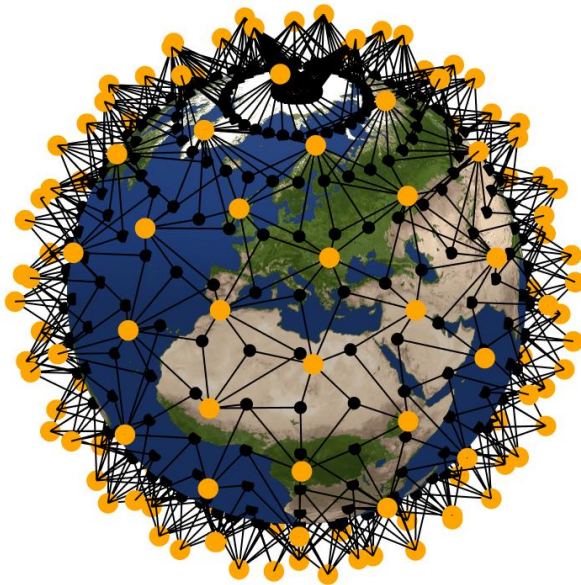
RMSE of 10 m zonal wind



# Graph-based MLWP<sup>1</sup>



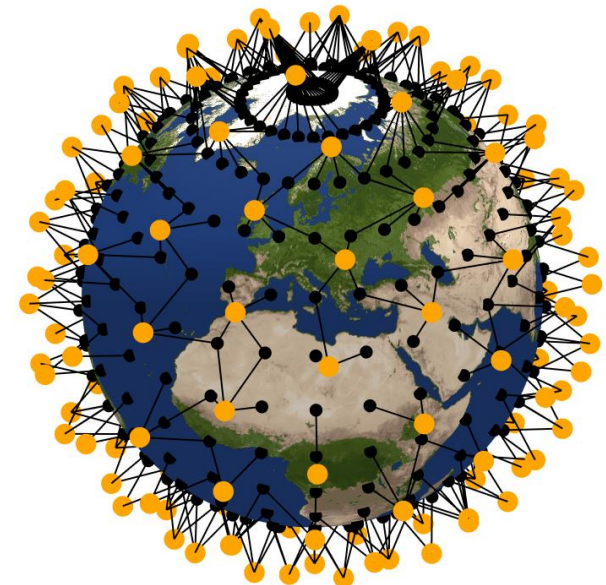
$$\hat{Y}_t = f_{\theta}(Y_{t-1})$$



Encode

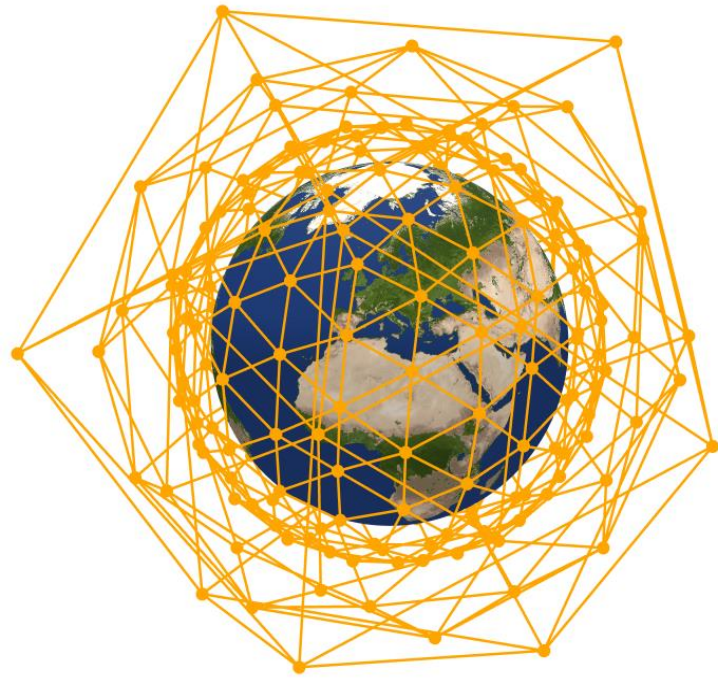



Mesh graph  
Process

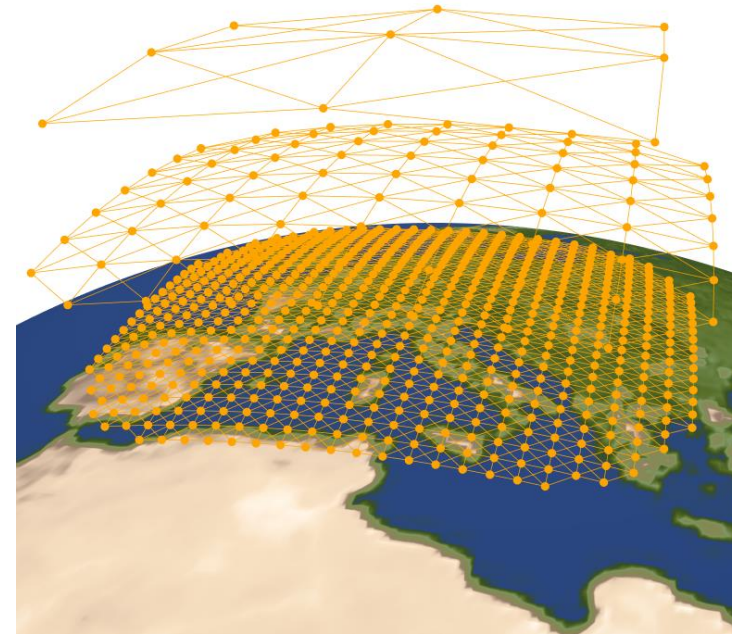




Decode

# Global and regional forecasting



Global model   
Hierarchical mesh graph

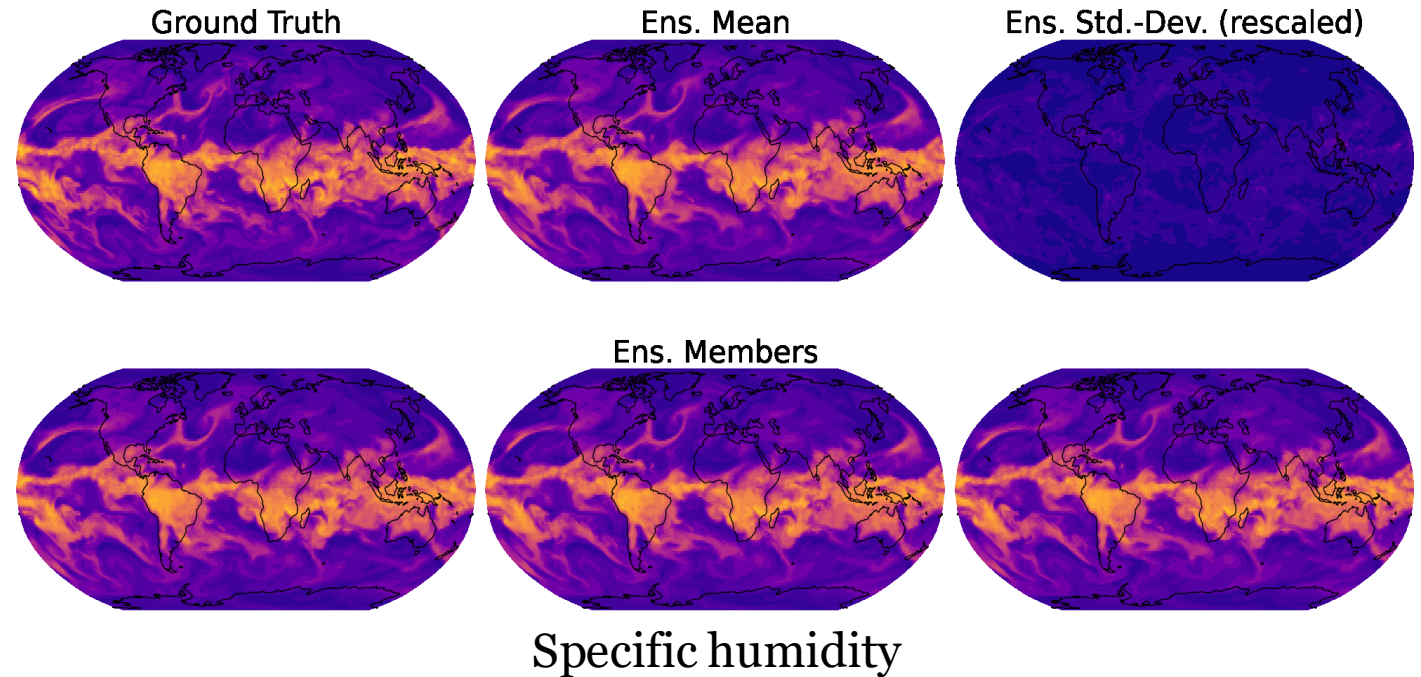


Limited area model    
Hierarchical mesh graph

# MLWP ensemble forecasting

$$p\left((Y_t)_{t=1}^T \middle| Y_0\right) = \prod_{t=1}^T p(Y_t | Y_{t-1})$$

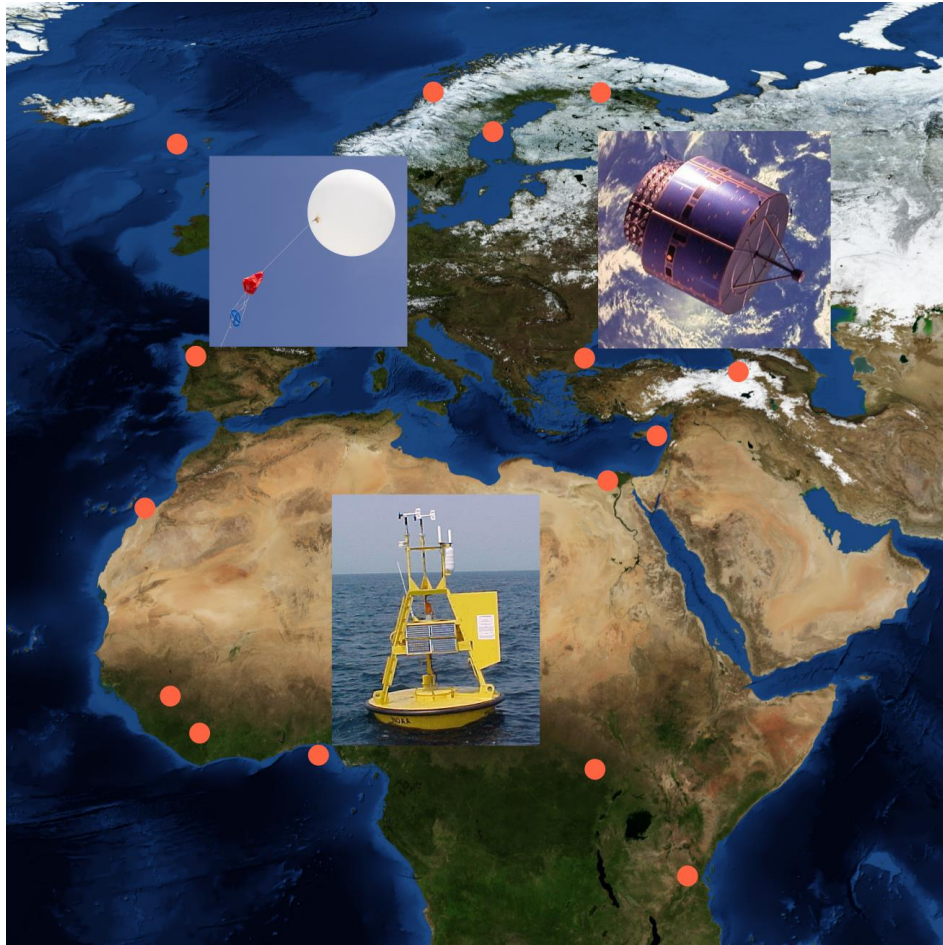
- Latent variable models<sup>1</sup>
- Diffusion models<sup>2</sup>



<sup>1</sup>Y. Hu, et al. (2023). *SwinVRNN: A data-driven ensemble forecasting model via learned distribution perturbation*. JAMES

<sup>2</sup>I. Price, et al. (2025). *Probabilistic weather forecasting with machine learning*. Nature.,  
 M. Andrae, et al. (2025). *Continuous Ensemble Weather Forecasting with Diffusion Models*. ICLR.,  
 E. Larsson, et al. (2025). *Diffusion-LAM: Probabilistic Limited Area Weather Forecasting with Diffusion*. CCAI Workshop @ ICLR.

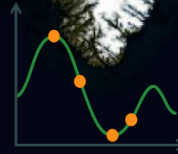
# Outlook



- Irregular observations
- Probabilistic forecasting
- MLWP directly using observations

# Modeling Spatio-Temporal Systems with Graph-based Machine Learning

Joel Oskarsson



Paper 1: J. Oskarsson, P. Sidén, and F. Lindsten. *Temporal graph neural networks for irregular data*. AISTATS, 2023



Paper 2: T. Westny, J. Oskarsson, B. Olofsson, and E. Frisk. *MTP-GO: Graph-based probabilistic multi-agent trajectory prediction with neural ODEs*. IEEE IV, 2023



Paper 3: J. Oskarsson, P. Sidén, and F. Lindsten. *Scalable deep Gaussian Markov random fields for general graphs*. ICML, 2022



Paper 4: J. Oskarsson, T. Landelius, M. P. Deisenroth, and F. Lindsten. *Probabilistic weather forecasting with hierarchical graph neural networks*. NeurIPS, 2024

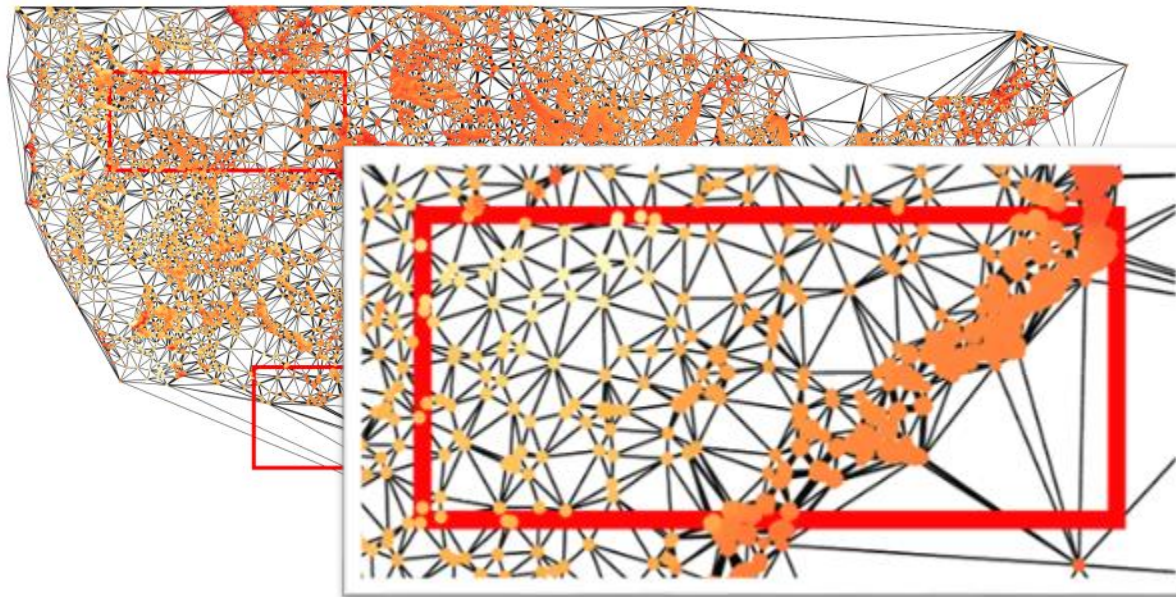


Paper 5: S. Adamov\*, J. Oskarsson\*, et al. *Building machine learning limited area models: Kilometer-scale weather forecasting in realistic settings*. Preprint, under review, 2025

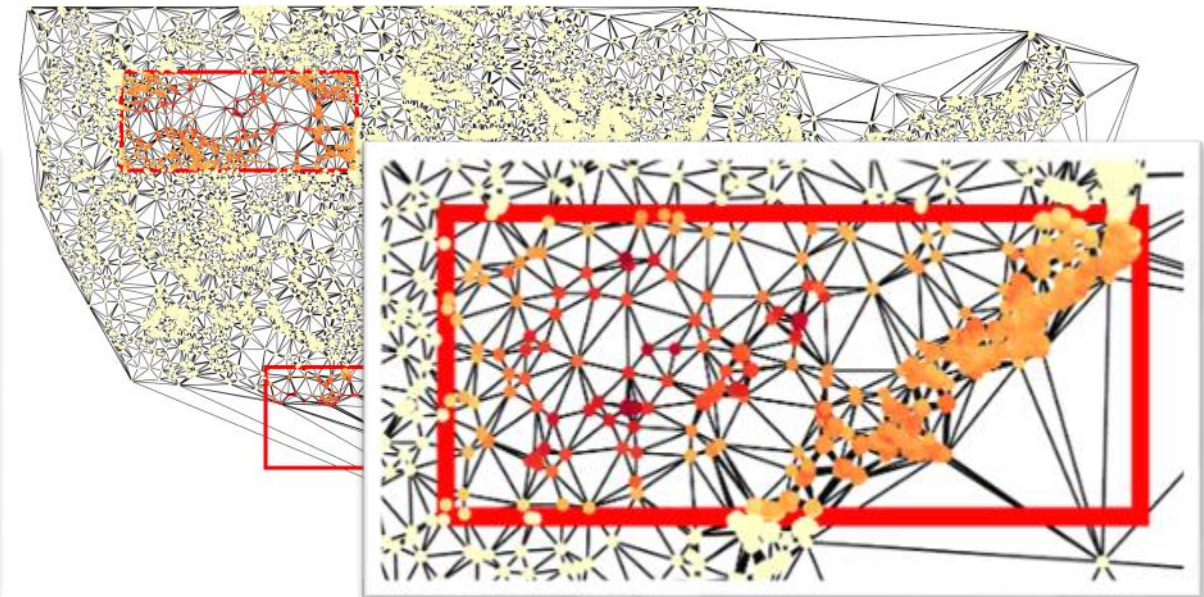
\* Equal contribution

# Example: Wind speeds

- Nodes in red boxes unobserved



Mean



Standard deviation